

Modeling Concurrent Systems

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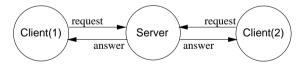
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A Client/Server System





- System of one server and two clients.
 - Three concurrently executing system components.
- Server manages a resource.
 - An object that only one system component may use at any time.
- Clients request resource and, having received an answer, use it.
 - Server ensures that not both clients use resource simultaneously.
 - Server eventually answers every request.

Set of system requirements.

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1. A Client/Server System

- 2. Modeling Concurrent Systems
- 3. A Model of the Client/Server System
- 4. Summary

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System Implementation

Server: local given, waiting, sender begin given := 0; waiting := 0 loop sender := receiveRequest() if sender = given then if waiting = 0 then given := 0 else given := waiting; waiting := 0 sendAnswer(given) endif elsif given = 0 then given := sender sendAnswer(given) else

waiting := sender

endif

endloop end Server

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Client(ident): param ident begin loop . . . sendRequest() receiveAnswer() ... // critical region sendRequest() endloop end Client



Property: mutual exclusion.

- At no time, both clients are in critical region.
 - Critical region: program region after receiving resource from server and before returning resource to server.
- The system shall only reach states, in which mutual exclusion holds.
- Property: no starvation.
 - Always when a client requests the resource, it eventually receives it.
 - Always when the system reaches a state, in which a client has requested a resource, it shall later reach a state, in which the client receives the resource.
- Problem: each system component executes its own program.
 - Multiple program states exist at each moment in time.
 - Total system state is combination of individual program states.
 - Not easy to see which system states are possible.

How can we verify that the system has the desired properties?

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System States



At each moment in time, a system is in a particular state.

- A state $s : Var \rightarrow Val$
 - A state s is a mapping of every system variable x to its value s(x).
 - Typical notation: s = [x = 0, y = 1, ...] = [0, 1, ...].
 - Var ... the set of system variables
 - Program variables, program counters, ...
 - Val ... the set of variable values.
- The state space $State = \{s \mid s : Var \rightarrow Val\}$
 - The state space is the set of possible states.
 - The system variables can be viewed as the coordinates of this space.
 - The state space may (or may not) be finite.
 - If |Var| = n and |Val| = m, then $|State| = m^n$.
 - A word of $\log_2 m^n$ bits can represent every state.

A system execution can be described by a path $s_0 \to s_1 \to s_2 \to \ldots$ in the state space.



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Deterministic Systems

In a sequential system, each state typically determines its successor state.

- **The system is deterministic**.
 - We have a (possibly not total) transition function F on states.
 - $s_1 = F(s_0)$ means " s_1 is the successor of s_0 ".
- Given an initial state s_0 , the execution is thus determined.

$$s_0 \rightarrow s_1 = F(s_0) \rightarrow s_2 = F(s_1) \rightarrow .$$

- A deterministic system (model) is a pair $\langle I, F \rangle$.
 - A set of initial states $I \subseteq State$
 - Initial state condition $I(s) :\Leftrightarrow s \in I$
 - A transition function $F : State \xrightarrow{partial} State$.
- A run of a deterministic system $\langle I, F \rangle$ is a (finite or infinite) sequence $s_0 \rightarrow s_1 \rightarrow \ldots$ of states such that
 - $s_0 \in I$ (respectively $I(s_0)$).
 - $s_{i+1} = F(s_i)$ (for all sequence indices i)
 - If s ends in a state s_n , then F is not defined on s_n .

Nondeterministic Systems



In a concurrent system, each component may change its local state, thus the successor state is not uniquely determined.

- **The system is nondeterministic**.
 - We have a transition relation *R* on states.
 - **R** (s_0, s_1) means " s_1 is a (possible) successor of s_0 .
- **Given** an initial state s_0 , the execution is not uniquely determined.
 - Both $s_0 \rightarrow s_1 \rightarrow \ldots$ and $s_0 \rightarrow s_1' \rightarrow \ldots$ are possible.
- A non-deterministic system (model) is a pair $\langle I, R \rangle$.
 - A set of initial states (initial state condition) $I \subseteq State$.
 - A transition relation $R \subseteq State \times State$.
- A run s of a nondeterministic system $\langle I, R \rangle$ is a (finite or infinite) sequence $s_0 \rightarrow s_1 \rightarrow s_2 \dots$ of states such that
 - $s_0 \in I$ (respectively $I(s_0)$).
 - **R** (s_i, s_{i+1}) (for all sequence indices *i*).
 - If s ends in a state s_n , then there is no state t such that $R(s_n, t)$.

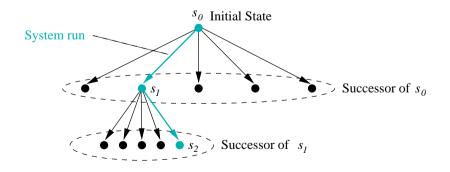
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Reachability Graph



The transitions of a system can be visualized by a graph.



The nodes of the graph are the reachable states of the system.

Derived Notions



- Successor and predecessor:
 - State t is a (direct) successor of state s, if R(s, t).
 - State *s* is then a predecessor of *t*.

A finite run $s_0 \rightarrow \ldots \rightarrow s_n$ ends in a state which has no successor.

- Reachability:
 - A state *t* is reachable, if there exists some run $s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \ldots$ such that $t = s_i$ (for some *i*).
 - A state *t* is unreachable, if it is not reachable.

Not all states are reachable (typically most are unreachable).

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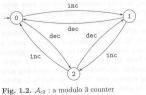
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Examples



Fig. 1.1. A model of a watch

of \mathcal{A}_{c3} correspond to the possible counter values. Its transitions reflect the possible actions on the counter. In this example we restrict our operations to increments (inc) and decrements (dec).

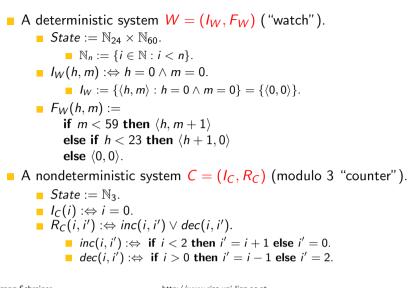


ig. 1.2. \mathcal{A}_{c3} : a modulo 3 counter and the second data second data second by a

B.Berard et al: "Systems and Software Verification", 2001.

Examples





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Initial States of Composed System



What are the initial states *I* of the composed system?

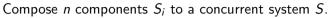
• Set $I := I_0 \times \ldots \times I_{n-1}$.

- *I_i* is the set of initial states of component *i*.
- Set of initial states is Cartesian product of the sets of initial states of the individual components.

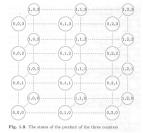
Predicate $I(s_0, \ldots, s_{n-1}) : \Leftrightarrow I_0(s_0) \land \ldots \land I_{n-1}(s_{n-1}).$

- *I_i* is the initial state condition of component *i*.
- Initial state condition is conjunction of the initial state conditions of the components on the corresponding projection of the state.

Size of initial state set is the product of the sizes of the initial state sets of the individual components.



- State space $State := State_0 \times \ldots \times State_{n-1}$.
 - *State*_i is the state space of component *i*.
 - State space is Cartesian product of component state spaces.
 - Size of state space is product of the sizes of the component spaces.
- **Example**: three counters with state spaces \mathbb{N}_2 and \mathbb{N}_3 and \mathbb{N}_4 .



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Transitions of Composed System

Which transitions can the composed system perform?

- Synchronized composition.
 - At each step, every component must perform a transition.
 - **R** $_i$ is the transition relation of component *i*.

 $R(\langle s_0, \ldots, s_{n-1} \rangle, \langle s'_0, \ldots, s'_{n-1} \rangle) :\Leftrightarrow R_0(s_0, s'_0) \land \ldots \land R_{n-1}(s_{n-1}, s'_{n-1})$

Asynchronous composition.

At each moment, every component may perform a transition.

- At least one component performs a transition.
- Multiple simultaneous transitions are possible
- With *n* components, $2^n 1$ possibilities of (combined) transitions.

 $R(\langle s_0, \ldots, s_{n-1} \rangle, \langle s'_0, \ldots, s'_{n-1} \rangle) :\Leftrightarrow$ $(R_0(s_0, s'_0) \wedge \ldots \wedge s_{n-1} = s'_{n-1}) \vee$ \ldots $(s_0 = s'_0 \wedge \ldots \wedge R_{n-1}(s_{n-1}, s'_{n-1})) \vee$ \ldots $(R_0(s_0, s'_0) \wedge \ldots \wedge R_{n-1}(s_{n-1}, s'_{n-1}))$

Example

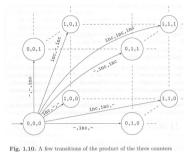


System of three counters with state space \mathbb{N}_2 each.

Synchronous composition:

 $[0,0,0] \leftrightarrows [1,1,1]$

Asynchronous composition:



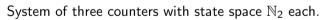
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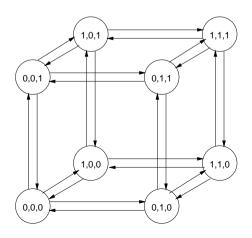
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Example





Interleaving Execution



Simplified view of asynchronous execution.

- At each moment, only one component performs a transition.
 - **Do not allow simultaneous transition** $t_i | t_i$ of two components *i* and *j*.
 - **Transition** sequences t_i ; t_j and t_j ; t_i are possible.
 - All possible interleavings of component transitions are considered.
 - Nondeterminism is used to simulate concurrency.
 - Essentially no change of system properties.
 - With *n* components, only *n* possibilities of a transition.

$$R(\langle s_{0}, s_{1}, \dots, s_{n-1} \rangle, \langle s'_{0}, s'_{1}, \dots, s'_{n-1} \rangle) :\Leftrightarrow \\ (R_{0}(s_{0}, s'_{0}) \wedge s_{1} = s'_{1} \wedge \dots \wedge s_{n-1} = s'_{n-1}) \vee \\ (s_{0} = s'_{0} \wedge R_{1}(s_{1}, s'_{1}) \wedge \dots \wedge s_{n-1} = s'_{n-1}) \vee \\ \dots \\ (s_{0} = s'_{0} \wedge s_{1} = s'_{1} \wedge \dots \wedge R_{n-1}(s_{n-1}, s'_{n-1})).$$

Interleaving model (respectively a variant of it) suffices in practice.

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Digital Circuits

Synchronous composition of hardware components.

• A modulo 8 counter $C = \langle I_C, R_C \rangle$.

State := $\mathbb{N}_2 \times \mathbb{N}_2 \times \mathbb{N}_2$.

$$I_C(v_0, v_1, v_2) :\Leftrightarrow v_0 = v_1 = v_2 = 0.$$

 $\begin{array}{l} R_{C}(\langle v_{0}, v_{1}, v_{2} \rangle, \langle v_{0}', v_{1}', v_{2}' \rangle) :\Leftrightarrow \\ R_{0}(v_{0}, v_{0}') \land \\ R_{1}(v_{0}, v_{1}, v_{1}') \land \\ R_{2}(v_{0}, v_{1}, v_{2}, v_{2}'). \end{array}$

 $\begin{array}{l} R_0(v_0, v_0') :\Leftrightarrow v_0' = \neg v_0. \\ R_1(v_0, v_1, v_1') :\Leftrightarrow v_1' = v_0 \oplus v_1. \\ R_2(v_0, v_1, v_2, v_2') :\Leftrightarrow v_2' = (v_0 \wedge v_1) \oplus v_2. \end{array}$

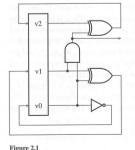


Figure 2.1 Synchronous modulo 8 counter. Edmund Clarke et al: "Model Checking", 1999.

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Concurrent Software



Asynchronous composition of software components with shared variables.

P:: h: while true do NC_0 : wait turn = 0 CR_0 : turn := 1 end

Q :: h_1 : while true do NC_1 : wait turn = 1 CR_1 : turn := 0 end

• A mutual exclusion program $M = \langle I_M, R_M \rangle$. State := $PC \times PC \times \mathbb{N}_2$. // shared variable $I_M(p, q, turn) :\Leftrightarrow p = I_0 \land q = I_1.$ $R_{M}(\langle p, q, turn \rangle, \langle p', q', turn' \rangle) :\Leftrightarrow$ $(P(\langle p, turn \rangle, \langle p', turn' \rangle) \land q' = q) \lor (Q(\langle q, turn \rangle, \langle q', turn' \rangle) \land p' = p).$ $P(\langle p, turn \rangle, \langle p', turn' \rangle) :\Leftrightarrow$ $(p = l_0 \land p' = NC_0 \land turn' = turn) \lor$ $(p = NC_0 \land p' = CR_0 \land turn = 0 \land turn' = turn) \lor$ $(p = CR_0 \wedge p' = l_0 \wedge turn' = 1).$ $Q(\langle q, turn \rangle, \langle q', turn' \rangle) :\Leftrightarrow$ $(q = l_1 \land q' = NC_1 \land turn' = turn) \lor$ $(q = NC_1 \land q' = CR_1 \land turn = 1 \land turn' = turn) \lor$ $(q = CR_1 \wedge q' = l_1 \wedge turn' = 0).$

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Modeling Commands

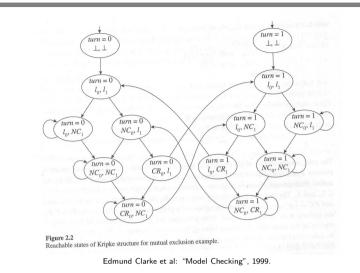


Transition relations are typically described in a particular form.

• $R(s,s') :\Leftrightarrow P(s) \land s' = F(s).$ Precondition P on state in which transition can be performed. If P(s) holds, then there exists some s' such that R(s, s'). **•** Transition function *F* that determines the successor of *s*. *F* is defined for all states for which *s* holds: $F : \{s \in State : P(s)\} \rightarrow State.$ Examples: • Assignment: $I: x := e; m : \ldots$ $\blacksquare R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow pc = l \land (x' = e \land y' = y \land pc' = m).$ • Wait statement: I: wait P(x, y); m: $\blacksquare R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow$ $pc = I \land P(x, y) \land (x' = x \land y' = y \land pc' = m).$ Guarded assignment: $I: P(x, y) \rightarrow x := e; m : \dots$ $\blacksquare R(\langle pc, x, y \rangle, \langle pc', x', y' \rangle) :\Leftrightarrow$ $pc = I \land P(x, y) \land (x' = e \land y' = y \land pc' = m).$ Most programming language commands can be translated into this form. Wolfgang Schreiner http://www.risc.uni-linz.ac.at 23/40

Concurrent Software





Model guarantees mutual exclusion.

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Modelling Message Passing Systems



How to model an asynchronous system without shared variables where the components communicate/synchronize by exchanging messages?

Given a label set $Label = Int \cup Ext \cup \overline{Ext}$.

- Disjoint sets Int and Ext of internal and external labels.
 - "Anonymous" label $_ \in Int$.
- Complementary label set $\overline{L} := \{\overline{I} : I \in L\}$.
- A labeled system is a pair $\langle I, R \rangle$.
 - Initial state condition $I \subseteq State$.
 - Labeled transition relation $R \subseteq Label \times State \times State$.
- A run of a labeled system $\langle I, R \rangle$ is a (finite or infinite) sequence

 $s_0 \xrightarrow{l_0} s_1 \xrightarrow{l_1} \ldots$ of states such that

*s*₀ ∈ *I*.

- $R(l_i, s_i, s_{i+1})$ (for all sequence indices *i*).
- If s ends in a state s_n , there is no label l and state t s.t. $R(l, s_n, t)$.

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Example

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\begin{array}{rl} 0 :: & \textbf{loop} & & \\ & a_0 : & \textbf{send}(i) & \\ & a_1 : & i := \textbf{receive}() & \\ & a_2 : & i := i+1 & \\ & \textbf{end} & \end{array}
```

Two labeled systems $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$. State₀ = State₁ = PC × N, Internal := {A, B}, External := {M, N}. $I_0(p, i) :\Leftrightarrow p = a_0 \land i \in \mathbb{N}; I_1(q, j) :\Leftrightarrow q = b_0.$ $R_0(I, \langle p, i \rangle, \langle p', i' \rangle) :\Leftrightarrow$ $(I = \overline{M} \land p = a_0 \land p' = a_1 \land i' = i) \lor$ $(I = N \land p = a_1 \land p' = a_2 \land i' = j) \lor // \text{illegal!}$ $(I = A \land p = a_2 \land p' = a_0 \land i' = i + 1).$ $R_1(I, \langle q, j \rangle, \langle q', j' \rangle) :\Leftrightarrow$ $(I = M \land q = b_0 \land q' = b_1 \land j' = i) \lor // \text{illegal!}$ $(I = B \land q = b_1 \land q' = b_2 \land j' = j + 1) \lor$ $(I = \overline{N} \land q = b_2 \land q' = b_0 \land j' = j).$

Synchronization by Message Passing



Compose a set of *n* labeled systems $\langle I_i, R_i \rangle$ to a system $\langle I, R \rangle$.

- **State space** $State := State_0 \times \ldots \times State_{n-1}$.
- Initial states $I := I_0 \times \ldots \times I_{n-1}$. $I(s_0, \ldots, s_{n-1}) :\Leftrightarrow I_0(s_0) \wedge \ldots \wedge I_{n-1}(s_{n-1})$.
- Transition relation

$$\begin{split} & R(I, \langle s_i \rangle_{i \in \mathbb{N}_n}, \langle s'_i \rangle_{i \in \mathbb{N}_n}) \Leftrightarrow \\ & (I \in Int \land \exists i \in \mathbb{N}_n : \\ & R_i(I, s_i, s'_i) \land \forall k \in \mathbb{N}_n \setminus \{i\} : s_k = s'_k) \lor \\ & (I = _ \land \exists I \in Ext, i \in \mathbb{N}_n, j \in \mathbb{N}_n : \\ & R_i(I, s_i, s'_i) \land R_j(\overline{I}, s_j, s'_j) \land \forall k \in \mathbb{N}_n \setminus \{i, j\} : s_k = s'_k). \end{split}$$

Either a component performs an internal transition or two components simultaneously perform an external transition with complementary labels.

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Example (Continued)

Composition of $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$ to $\langle I, R \rangle$.

 $State = (PC \times \mathbb{N}) \times (PC \times \mathbb{N}).$

 $I(p, i, q, j) :\Leftrightarrow p = a_0 \land i \in \mathbb{N} \land q = b_0.$

 $\begin{array}{l} R(I, \langle p, i, q, j \rangle, \langle p', i', q', j' \rangle) : \Leftrightarrow \\ (I = A \land (p = a_2 \land p' = a_0 \land i' = i + 1) \land (q' = q \land j' = j)) \lor \\ (I = B \land (p' = p \land i' = i) \land (q = b_1 \land q' = b_2 \land j' = j + 1)) \lor \\ (I = _ \land (p = a_0 \land p' = a_1 \land i' = i) \land (q = b_0 \land q' = b_1 \land j' = i)) \lor \\ (I = _ \land (p = a_1 \land p' = a_2 \land i' = j) \land (q = b_2 \land q' = b_0 \land j' = j)). \end{array}$

Problem: state relation of each component refers to local variable of other component (variables are shared).

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Example (Revised)



- 0 :: **loop** 1 :: **loop** $b_0: i :=$ **receive()** a_0 : send(i) $a_1: i :=$ **receive**() $b_1: i:=i+1$ $a_2: i:=i+1$ b_2 : send(j) end end
- **Two labeled systems** $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$.

$$\begin{aligned} \text{External} &:= \{M_k : k \in \mathbb{N}\} \cup \{N_k : k \in \mathbb{N}\}.\\ R_0(I, \langle p, i \rangle, \langle p', i' \rangle) :\Leftrightarrow \\ & (I = \overline{M_i} \land p = a_0 \land p' = a_1 \land i' = i) \lor \\ & (\exists k \in \mathbb{N} : I = N_k \land p = a_1 \land p' = a_2 \land i' = k) \lor \\ & (I = A \land p = a_2 \land p' = a_0 \land i' = i + 1).\\ R_1(I, \langle q, j \rangle, \langle q', j' \rangle) :\Leftrightarrow \\ & (\exists k \in \mathbb{N} : I = M_k \land q = b_0 \land q' = b_1 \land j' = k) \lor \\ & (I = B \land q = b_1 \land q' = b_2 \land j' = j + 1) \lor \\ & (I = \overline{N_j} \land q = b_2 \land q' = b_0 \land j' = j). \end{aligned}$$

Encode message value in label. Wolfgang Schreiner http://www.risc.uni-linz.ac.at

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The Client/Server System



Asynchronous composition of three components *Client*₁, *Client*₂, *Server*.

- Client_i: State := $PC \times \mathbb{N}_2 \times \mathbb{N}_2$.
 - Three variables *pc*, *request*, *answer*.
 - *pc* represents the program counter.
 - *request* is the buffer for outgoing requests.
 - Filled by client, when a request is to be sent to server.
 - *answer* is the buffer for incoming answers.
 - Checked by client, when it waits for an answer from the server.
- Server: State := $(\mathbb{N}_3)^3 \times (\{1,2\} \to \mathbb{N}_2)^2$.
 - Variables given, waiting, sender, rbuffer, sbuffer.
 - No program counter.
 - We use the value of *sender* to check whether server waits for a request (sender = 0) or answers a request (sender \neq 0).
 - Variables given, waiting, sender as in program.
 - *rbuffer(i)* is the buffer for incoming requests from client *i*.
 - sbuffer(i) is the buffer for outgoing answers to client i.

Composition of $\langle I_0, R_0 \rangle$ and $\langle I_1, R_1 \rangle$ to $\langle I, R \rangle$.

$$\begin{aligned} State &= (PC \times \mathbb{N}) \times (PC \times \mathbb{N}). \\ l(p, i, q, j) &:\Leftrightarrow p = a_0 \land i \in \mathbb{N} \land q = b_0. \\ R(l, \langle p, i, q, j \rangle, \langle p', i', q', j' \rangle) &:\Leftrightarrow \\ (l &= A \land (p = a_2 \land p' = a_0 \land i' = i + 1) \land (q' = q \land j' = j)) \lor \\ (l &= B \land (p' = p \land i' = i) \land (q = b_1 \land q' = b_2 \land j' = j + 1)) \lor \\ (l &= _ \land \exists k \in \mathbb{N} : k = i \land \\ (p = a_0 \land p' = a_1 \land i' = i) \land (q = b_0 \land q' = b_1 \land j' = k)) \lor \\ (l &= _ \land \exists k \in \mathbb{N} : k = j \land \end{aligned}$$

Logically equivalent to previous definition of transition relation.

 $(p = a_1 \land p' = a_2 \land i' = k) \land (q = b_2 \land q' = b_0 \land j' = j)).$

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External Transitions

- $Ext := \{REQ_1, REQ_2, ANS_1, ANS_2\}.$
 - Transition labeled REQ; transmits a request from client i to server.
 - Enabled when request $\neq 0$ in client *i*.
 - Effect in client *i*: request' = 0.
 - Effect in server: rbuffer'(i) = 1.
 - Transition labeled ANS; transmits an answer from server to client i
 - Enabled when $sbuffer(i) \neq 0$.
 - Effect in server: sbuffer'(i) = 0.
 - Effect in client *i*: answer' = 1.

The external transitions correspond to system-level actions of the communication subsystem (rather than to the user-level actions of the client/server program).







V

The Client



Client system $C_i = \langle IC_i, RC_i \rangle$.

 $\begin{array}{l} \textit{State} := \textit{PC} \times \mathbb{N}_2 \times \mathbb{N}_2.\\ \textit{Int} := \{\textit{R}_i, \textit{S}_i, \textit{C}_i\}.\\ \\ \textit{IC}_i(\textit{pc}, \textit{request}, \textit{answer}) :\Leftrightarrow\\ \textit{pc} = \textit{R} \land \textit{request} = \textit{0} \land \textit{answer} = \textit{0}.\\ \\ \textit{RC}_i(\textit{I}, \langle\textit{pc}, \textit{request}, \textit{answer} \rangle, \\ \langle\textit{pc}', \textit{request}', \textit{answer} \rangle) :\Leftrightarrow\\ (\textit{I} = \textit{R}_i \land \textit{pc} = \textit{R} \land \textit{request} = \textit{0} \land \\ \textit{pc}' = \textit{S} \land \textit{request}' = \textit{1} \land \textit{answer}' = \textit{answer}) \lor \\ (\textit{I} = \textit{S}_i \land \textit{pc} = \textit{S} \land \textit{answer} \neq \textit{0} \land \\ \textit{pc}' = \textit{C} \land \textit{request}' = \textit{request} \land \textit{answer}' = \textit{0}) \lor \\ \\ \textit{pc}' = \textit{C} \land \textit{request}' = \textit{c} \land \textit{answer}' = \textit{0} \land \\ \\ \textit{pc}' = \textit{R} \land \textit{request}' = \textit{1} \land \textit{answer}' = \textit{answer}) \lor \\ \\ \\ \textit{pc}' = \textit{R} \land \textit{request}' = \textit{1} \land \textit{answer}' = \textit{answer}) \lor \\ \end{aligned}$

param ident begin loop ... R: sendRequest() S: receiveAnswer() C: // critical region ... sendRequest() endloop end Client

Client(ident):

```
      (I = \overline{REQ_i} \land request \neq 0 \land \\ pc' = pc \land request' = 0 \land answer' = answer) \lor \\ (I = ANS_i \land \\ pc' = pc \land request' = request \land answer' = 1).
```

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The Server (Contd)



local given, waiting, sender

given := 0; waiting := 0

- $\begin{array}{l} (I = F \land sender \neq 0 \land sender = given \land waiting = 0 \land given' = 0 \land sender' = 0 \land U(waiting, rbuffer, sbuffer)) \lor \\ (I = A1 \land sender \neq 0 \land sbuffer(waiting) = 0 \land sender = given \land waiting \neq 0 \land given' = waiting \land waiting' = 0 \land sbuffer'(waiting) = 1 \land sender' = 0 \land U(rbuffer) \land \forall j \in \{1, 2\} \backslash \{waiting\} : U_j(sbuffer)) \lor \\ (I = A2 \land sender \neq 0 \land sbuffer(sender) = 0 \land sender \neq given \land given' = sender \land given' = sender \land sbuffer'(sender) = 1 \land sender' = 0 \land given' = sender \land sbuffer'(sender) = 1 \land sender' = 0 \land \end{array}$
 - loop D: sender := receiveRequest() if sender = given then if waiting = 0 then F: given := 0 else A1: given := waiting: waiting := 0 sendAnswer(given) endif elsif given = 0 then A2: given := sender sendAnswer(given) else W: waiting := sender endif endloop end Server

Server:

begin

The Server

Server system $S = \langle IS, RS \rangle$.

 $\begin{array}{l} \textit{State} := (\mathbb{N}_3)^3 \times (\{1,2\} \to \mathbb{N}_2)^2. \\ \textit{Int} := \{\textit{D1},\textit{D2},\textit{F},\textit{A1},\textit{A2},\textit{W}\}. \end{array}$

```
IS(given, waiting, sender, rbuffer, sbuffer) :\Leftrightarrow

given = waiting = sender = 0 \land

rbuffer(1) = rbuffer(2) = sbuffer(1) = sbuffer(2) = 0.
```

$$\begin{split} &RS(I, \langle given, waiting, sender, rbuffer, sbuffer \rangle, \\ &\langle given', waiting', sender', rbuffer', sbuffer' \rangle) :\Leftrightarrow \\ &\exists i \in \{1,2\} : \\ &(I = D_i \land sender = 0 \land rbuffer(i) \neq 0 \land \\ &sender' = i \land rbuffer'(i) = 0 \land \\ &U(given, waiting, sbuffer) \land \\ &\forall j \in \{1,2\} \backslash \{i\} : U_j(rbuffer)) \lor \end{split}$$

```
U(x_1, \dots, x_n) :\Leftrightarrow x'_1 = x_1 \wedge \dots \wedge x'_n = x_n.
U_j(x_1, \dots, x_n) :\Leftrightarrow x'_1(j) = x_1(j) \wedge \dots \wedge x'_n(j) = x_n(j).
```

```
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```

The Server (Contd'2)

...

 $(I = W \land sender \neq 0 \land sender \neq given \land given \neq 0 \land$ waiting' := sender $\land sender' = 0 \land$ $U(given, rbuffer, sbuffer)) \lor$

$\exists i \in \{1,2\}$:

 $\begin{array}{l} (I = REQ_i \land rbuffer'(i) = 1 \land \\ U(given, waiting, sender, sbuffer) \land \\ \forall j \in \{1, 2\} \backslash \{i\} : U_j(rbuffer)) \lor \end{array}$

Server:

```
local given, waiting, sender
begin
 given := 0; waiting := 0
 loop
```

```
D: sender := receiveRequest()
    if sender = given then
        if waiting = 0 then
```

```
F: given := 0
else
```

```
A1: given := waiting;
waiting := 0
sendAnswer(given)
endif
```

```
elsif given = 0 then
A2: given := sender
```

```
sendAnswer(given)
else
```

```
W: waiting := sender
endif
endloop
end Server
```

```
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```



Server:

local given, waiting, sender begin

```
given := 0; waiting := 0
loop
```

```
D: sender := receiveRequest()
    if sender = given then
        if waiting = 0 then
```

```
F: given := 0
else
```

```
A1: given := waiting;
waiting := 0
sendAnswer(given)
endif
elsif given = 0 then
```

```
A2: given := sender
sendAnswer(given)
else
```

```
W: waiting := sender
endif
endloop
```

end Server

 $U(waiting, rbuffer) \land$

 $\forall j \in \{1, 2\} \setminus \{sender\} : U_i(sbuffer)) \lor$

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Communication Channels



We also model the communication medium between components.



Bounded channel Channel_{i,j} = (ICH, RCH).
Transfers message from component with address *i* to component *j*.
May hold at most *N* messages at a time (for some *N*).
State := ⟨Value⟩.
Sequence of values of type Value.
Ext := {SEND_{i,j}(m) : m ∈ Value} ∪ {RECEIVE_{i,j}(m) : m ∈ Value}.
By SEND_{i,j}(m), channel receives from sender *i* a message *m* destined for receiver *j*; by RECEIVE_{i,j}(m), channel forwards that message.
ICH(queue) :⇔ queue = ⟨⟩.
RCH(I, queue, queue') :⇔
∃*i* ∈ Address, *j* ∈ Address, *m* ∈ Value :
(*I* = SEND_{i,i}(m) ∧ |queue| < N ∧ queue' = queue ∘ ⟨m⟩) ∨

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 $(I = \overline{RECEIVE}_{i,i}(m) \land |queue| > 0 \land queue = \langle m \rangle \circ queue').$

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- 1. A Client/Server System
- 2. Modeling Concurrent Systems
- 3. A Model of the Client/Server System

4. Summary

Client/Server Example with Channels



- Server receives address 0.
 - Label REQ_i is renamed to $RECEIVE_{i,0}(R)$.
 - Label $\overline{ANS_i}$ is renamed to $\overline{SEND_{0,i}(A)}$.
- Client *i* receives address *i* ($i \in \{1, 2\}$).
 - Label $\overline{REQ_i}$ is renamed to $\overline{SEND_{i,0}(R)}$.
 - Label ANS_i is renamed to $RECEIVE_{0,i}(A)$.
- System is composed of seven components:
 - Server, Client₁, Client₂.
 - Channel_{0,1}, Channel_{1,0}.
 - Channel_{0,2}, Channel_{2,0}.

Client(1) request answer Server answer Client(2)

Also channels are active system components.

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Summary

- A system is described by
 - its (finite or infinite) state space,
 - the initial state condition (set of input states),
 - the transition relation on states.
- State space of composed system is product of component spaces.
 - Variable shared among components occurs only once in product.
- System composition can be
 - **synchronous**: conjunction of individual transition relations.
 - Suitable for digital hardware.
 - **asynchronous**: disjunction of relations.
 - Interleaving model: each relation conjoins the transition relation of one component with the identity relations of all other components.
 - Suitable for concurrent software.
- Message passing systems may be modeled by using labels:
 - Synchronize transitions of sender and receiver.
 - Carry values to be transmitted from sender to receiver.

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